Leica TS13



User Manual Version 2.0 English

- when it has to be **right**



Introduction

| Purchase | Congratulations on the purchase of the Leica TS13. | | | | |
|----------------------------|---|--|-----------|-------------------|--|
| ĺĺ | This manual contains important safety directions as well as instructions for setting up the product and operating it. Refer to "1 Safety Directions" for fur-ther information. | | | s for for fur- | |
| | Read carefully through | the User Manual before you switch on t | :he prod | uct. | |
| - | The content of this do that the product is use ment. | he content of this document is subject to change without prior notice. Ensure hat the product is used in accordance with the latest version of this docunent. | | | |
| | Updated versions are a | vailable for download at the following Ir | iternet a | address: | |
| _ | https://myworld.leica | a-geosystems.com > myDownloads. | | | |
| Product identification | The model and serial n | umber of your product are indicated on | the type | the type plate. | |
| | Always refer to this inf Leica Geosystems auth | formation when you need to contact you porised service centre. | ır agenc | y or | |
| Trademarks | Windows is a registered trademark of Microsoft Corporation in the United States and other countries Bluetooth[®] is a registered trademark of Bluetooth SIG, Inc. | | | United | |
| | SD Logo is a trade | mark of SD-3C, LLC. | rc | | |
| _ | | e the property of their respective owne | 15. | | |
| Validity of this manual | This manual applies to the TS13. | | | | |
| Available documentation | Name | Description/Format | | | |
| | TS13 Quick Guide | Provides an overview of the product together with technical data and safety directions. Intended as a quick reference guide. | ~ | ✓ | |
| | TS13 User Manual | All instructions required in order to operate the product to a basic level are contained in the User Manual. Provides an overview of the product together with technical data and safety directions. | - | ✓ | |
| | Name | Description/Format | | | |
| | Captivate Technical Reference Manual | Overall comprehensive guide to the product and apps. Included are detailed descriptions of special soft- ware/hardware settings and soft- ware/hardware functions intended for technical specialists. | - | ✓ | |

Refer to the following resources for documentation/software:

- the Leica Captivate USB documentation card
- https://myworld.leica-geosystems.com

Video tutorials are available on:



http://www.leica-geosystems.com/captivate-howto

Leica Geosystems address book

On the last page of this manual, you can find the address of Leica Geosystems headquarters. For a list of regional contacts, please visit **http://leica-geosystems.com/contact-us/sales_support**.

world

myWorld@Leica Geosystems (https://myworld.leica-geosystems.com) offers a wide range of services, information and training material.

With direct access to myWorld, you are able to access all relevant services whenever it is convenient for you.

| Service | Description |
|-------------------|--|
| myProducts | Add all products that you and your company own and explore your world of Leica Geosystems: View detailed information on your products and update your products with the latest software and keep up- to-date with the latest documentation. |
| myService | View the current service status and full service his- tory of your products in Leica Geosystems service centres. Access detailed information on the services performed and download your latest calibration cer- tificates and service reports. |
| mySupport | Create new support requests for your products that will be answered by your local Leica Geosystems Support Team. View the complete history of your support requests and view detailed information on each request in case you want to refer to previous support requests. |
| myTraining | Enhance your product knowledge with Leica Geosys- tems Campus - Information, Knowledge, Training. Study the latest online training material on your products and register for seminars or courses in your country. |
| myTrustedServices | Add your subscriptions and manage users for Leica Geosystems Trusted Services, the secure software services, that assist you to optimise your workflow and increase your efficiency. |

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| | Safety Directions | | |
|--|--|---|--|
| 1.1 | General Introducti | General Introduction | |
| Description | The following directions the person who actually tional hazards. | enable the person responsible for the product, and vuses the equipment, to anticipate and avoid opera- | |
| | The person responsible these directions and ad | for the product must ensure that all users understand here to them. | |
| About warning messagesWarning messages are an essential part of the safety conce ment. They appear wherever hazards or hazardous situation | | an essential part of the safety concept of the instru- rever hazards or hazardous situations can occur. | |
| | Warning messages | | |
| | make the user alert of the product. contain general rule | about direct and indirect hazards concerning the use of behaviour. | |
| | For the users' safety, all safety instructions and safety messages sha strictly observed and followed! Therefore, the manual must always t to all persons performing any tasks described here. | | |
| | DANGER, WARNING, C identifying levels of haz damage. For your safety lowing table with the di ary safety information s well as supplementary t | AUTION and NOTICE are standardised signal words for ards and risks related to personal injury and property y, it is important to read and fully understand the fol- fferent signal words and their definitions! Supplement- symbols may be placed within a warning message as ext. | |
| Туре | | Description | |
| | | Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. | |
| | A WARNING | Indicates a potentially hazardous situation or an unintended use which, if not avoided, could result in death or serious injury. | |
| | | Indicates a potentially hazardous situation or an unintended use which, if not avoided, may result in minor or moderate injury. | |
| | ΝΟΤΙϹΕ | Indicates a potentially hazardous situation or an unintended use which, if not avoided, may result in appreciable material, financial and environmental damage. | |
| | | Important paragraphs which must be | |

| 1.2 | Definition of Use |
|---------------------------------|---|
| Intended use | Measuring horizontal and vertical angles Measuring distances Recording measurements Automatic target search, recognition and tracking Visualising the aiming direction and vertical axis Remote control of product Data communication with external appliances Measuring raw data and computing coordinates using carrier phase and code signal from GNSS satellites (GNSS systems) Recording GNSS and point related data Computing with software |
| Reasonably forseeable misuse | Use of the product without instruction. Use outside of the intended use and limits. Disabling safety systems. Removal of hazard notices. Opening the product using tools, for example screwdriver, unless this is permitted for certain functions. Modification or conversion of the product. Use after misappropriation. Use of products with recognisable damage or defects. Use with accessories from other manufacturers without the prior explicit approval of Leica Geosystems. Deliberate dazzling of third parties. Controlling of machines, moving objects or similar monitoring application without additional control and safety installations. Aiming directly into the sun. Inadequate safeguards at the working site. |
| 1.3 | Limits of Use |
| Environment | Suitable for use in an atmosphere appropriate for permanent human habita- tion: not suitable for use in aggressive or explosive environments. |
| | |
| | Working in hazardous areas, or close to electrical installations or similar situations Life Risk. Precautions: Local safety authorities and safety experts must be contacted by the person responsible for the product before working in such conditions. |
| 1.4 | Responsibilities |
| Manufacturer of the product | Leica Geosystems AG, CH-9435 Heerbrugg, hereinafter referred to as Leica Geosystems, is responsible for supplying the product, including the User Manual and original accessories, in a safe condition. |

Person responsible for the product

The person responsible for the product has the following duties:

- To understand the safety instructions on the product and the instructions in the User Manual.
- To ensure that it is used in accordance with the instructions.
- To be familiar with local regulations relating to safety and accident prevention.
- To inform Leica Geosystems immediately if the product and the application becomes unsafe.
- To ensure that the national laws, regulations and conditions for the operation of the product are respected.

1.5 Hazards of Use

NOTICE

Dropping, misusing, modifying, storing the product for long periods or transporting the product

Watch out for erroneous measurement results.

Precautions:

 Periodically carry out test measurements and perform the field adjustments indicated in the User Manual, particularly after the product has been subjected to abnormal use as well as before and after important measurements.

ADANGER

Risk of electrocution

Because of the risk of electrocution, it is dangerous to use poles, levelling staffs and extensions in the vicinity of electrical installations such as power cables or electrical railways.

Precautions:

Keep at a safe distance from electrical installations. If it is essential to work in this environment, first contact the safety authorities responsible for the electrical installations and follow their instructions.



Lightning strike

If the product is used with accessories, for example masts, staffs, poles, you may increase the risk of being struck by lightning.

Precautions:

• Do not use the product in a thunderstorm.

WARNING

Distraction/loss of attention

During dynamic applications, for example stakeout procedures, there is a danger of accidents occurring if the user does not pay attention to the environmental conditions around, for example obstacles, excavations or traffic.

Precautions:

The person responsible for the product must make all users fully aware of the existing dangers.

Inadequate securing of the working site

This can lead to dangerous situations, for example in traffic, on building sites and at industrial installations.

Precautions:

- Always ensure that the working site is adequately secured.
- Adhere to the regulations governing safety, accident prevention and road traffic.

Pointing product toward the sun

Be careful when pointing the product toward the sun, because the telescope functions as a magnifying glass and can injure your eyes and/or cause damage inside the product.

Precautions:

• Do not point the product directly at the sun.

Not properly secured accessories

If the accessories used with the product are not properly secured and the product is subjected to mechanical shock, for example blows or falling, the product may be damaged or people can sustain injury.

Precautions:

- When setting up the product, make sure that the accessories are correctly adapted, fitted, secured, and locked in position.
- Avoid subjecting the product to mechanical stress.

Inappropriate mechanical influences to batteries

During the transport, shipping or disposal of batteries it is possible for inappropriate mechanical influences to constitute a fire hazard.

Precautions:

- Before shipping the product or disposing it, discharge the batteries by the product until they are flat.
- When transporting or shipping batteries, the person in charge of the product must ensure that the applicable national and international rules and regulations are observed.
- Before transportation or shipping, contact your local passenger or freight transport company.

Exposure of batteries to high mechanical stress, high ambient temperatures or immersion into fluids

This can cause leakage, fire or explosion of the batteries.

Precautions:

 Protect the batteries from mechanical influences and high ambient temperatures. Do not drop or immerse batteries into fluids.

Short circuit of battery terminals

If battery terminals are short circuited e.g. by coming in contact with jewellery, keys, metallised paper or other metals, the battery can overheat and cause injury or fire, for example by storing or transporting in pockets.

Precautions:

 Make sure that the battery terminals do not come into contact with metallic objects.

WARNING

Moving parts at the product during operation

Risk of squeezing extremities or entanglement of hair and/or clothes. **Precautions:**

Keep a safe distance to the moving parts.

Improper disposal

If the product is improperly disposed of, the following can happen:

- If polymer parts are burnt, poisonous gases are produced which may impair health.
- If batteries are damaged or are heated strongly, they can explode and cause poisoning, burning, corrosion or environmental contamination.
- By disposing of the product irresponsibly you may enable unauthorised persons to use it in contravention of the regulations, exposing themselves and third parties to the risk of severe injury and rendering the environment liable to contamination.
- Improper disposal of silicone oil may cause environmental contamination.
- The product does include parts of Beryllium inside. Any modification of some internal parts can release Beryllium dust or fragments, creating a health hazard.

Precautions:



The product must not be disposed with household waste. Dispose of the product appropriately in accordance with the national regulations in force in your country. Always prevent access to the product by unauthorised personnel.

Product-specific treatment and waste management information can be received from your Leica Geosystems distributor.

Improperly repaired equipment

Risk of injuries to users and equipment destruction due to lack of repair knowledge.

Precautions:

 Only authorised Leica Geosystems Service Centres are entitled to repair these products.

| 1.6 | Laser Classification | |
|-------|----------------------|--|
| 1.6.1 | General | |
| | | |

General

The following chapters provide instructions and training information about laser safety according to international standard IEC 60825-1 (2014-05) and technical report IEC TR 60825-14 (2004-02). The information enables the person responsible for the product and the person who actually uses the equipment, to anticipate and avoid operational hazards.

- According to IEC TR 60825-14 (2004-02), products classified as laser class 1, class 2 and class 3R do not require:
 - laser safety officer involvement,
 - protective clothes and eyewear,
 - special warning signs in the laser working area

if used and operated as defined in this User Manual due to the low eye hazard level.

National laws and local regulations could impose more stringent instructions for the safe use of lasers than IEC 60825-1 (2014-05) and IEC TR 60825-14 (2004-02).

| 1.6.2 | Distancer, Measurements with Reflec | Distancer, Measurements with Reflectors | | |
|---------|--|--|--|--|
| General | The EDM module built into the product produce emerges from the telescope objective. | The EDM module built into the product produces a visible laser beam which emerges from the telescope objective. | | |
| | The laser product described in this section is accordance with: • IEC 60825-1 (2014-05): "Safety of laser | The laser product described in this section is classified as laser class 1 in accordance with: • IEC 60825-1 (2014-05): "Safety of laser products" | | |
| | These products are safe under reasonably fo and are not harmful to the eyes provided tha maintained in accordance with this User Man | These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual. | | |
| | Description | Value | | |
| | Wavelength | 658 nm | | |
| | Pulse duration | 800 ps | | |
| | Pulse repetition frequency (PRF) | 100 MHz | | |
| | Maximum average radiant power | 0.33 mW | | |
| | Beam divergance | 1.5 mrad × 3 mrad | | |



1.6.3 Distancer, Measurements without Reflectors General The EDM module built into the product produces a visible laser beam which emerges from the telescope objective. The laser product described in this section is classified as laser class 3R in

The laser product described in this section is classified as laser class 3R in accordance with:

IEC 60825-1 (2014-05): "Safety of laser products"

Direct intrabeam viewing may be hazardous (low eye hazard level), in particular for deliberate ocular exposure. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions. The risk of injury for laser class 3R products is limited because of:

•

- a) unintentional exposure would rarely reflect worst case conditions of (e.g.) beam alignment with the pupil, worst case accommodation,
- b) inherent safety margin in the maximum permissible exposure to laser radiation (MPE)
- c) natural aversion behaviour for exposure to bright light for the case of visible radiation.

| Description | Value (R500/R1000) |
|--|-----------------------|
| Wavelength | 658 nm |
| Maximum average radiant power | 4.8 mW |
| Pulse duration | 800 ps |
| Pulse repetition frequency (PRF) | 100 MHz |
| Beam divergence | 0.2 mrad x 0.3 mrad |
| NOHD (Nominal Ocular Hazard Distance) @ 0.25 s | 44 m / 144 ft |

Class 3R laser products

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- Prevent direct eye exposure to the beam.
- Do not direct the beam at other people.

Reflected beams aimed at reflecting surfaces

Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

Precautions:

- Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.

Labelling



1.6.4 Red Laser Pointer

General

The laser pointer built into the product produces a visible red laser beam which emerges from the telescope objective.

The laser product described in this section is classified as laser class 3R in accordance with:

• IEC 60825-1 (2014-05): "Safety of laser products"

Direct intrabeam viewing may be hazardous (low eye hazard level), in particular for deliberate ocular exposure. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions. The risk of injury for laser class 3R products is limited because of:

- a) unintentional exposure would rarely reflect worst case conditions of (e.g.) beam alignment with the pupil, worst case accommodation,
- b) inherent safety margin in the maximum permissible exposure to laser radiation (MPE)
- c) natural aversion behaviour for exposure to bright light for the case of visible radiation.

| Description | Value (R500/R1000) |
|-------------------------------|-----------------------|
| Wavelength | 658 nm |
| Maximum average radiant power | 4.8 mW |
| Pulse duration | 800 ps |

| Description | Value (R500/R1000) |
|--|-----------------------|
| Pulse repetition frequency (PRF) | 100 MHz |
| Beam divergence | 0.2 mrad x 0.3 mrad |
| NOHD (Nominal Ocular Hazard Distance) @ 0.25 s | 44 m / 144 ft |

Class 3R laser products

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- Prevent direct eye exposure to the beam.
- Do not direct the beam at other people.

Reflected beams aimed at reflecting surfaces

Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

Precautions:

- Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.



Labelling



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1.6.5 Automatic Target Aiming ATR

General

The Automatic Target Aiming built into the product produces an invisible laser beam which emerges from the telescope objective.

The laser product described in this section is classified as laser class 1 in accordance with:

• IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual.

| Description | Value |
|--------------------------------------|--------------|
| Wavelength | 785 nm |
| Maximum radiant peak power per pulse | 10 mW |
| Pulse duration | \leq 15 ms |
| Pulse repetition frequency (PRF) | ≤ 213 Hz |
| Beam divergence | 25 mrad |
| | |



| 1.6.6 | SpeedSearch | | |
|--------------|---|--|--|
| Availability | For this functionality, the TS13 Robotic licenc | For this functionality, the TS13 Robotic licence must be purchased. | |
| General | The SpeedSearch built into the product produces an invisible laser beam which emerges from the front side of the telescope. | | |
| | The laser product described in this section is classified as laser class 1 in accordance with: • IEC 60825-1 (2014-05): "Safety of laser products" | | |
| | These products are safe under reasonably for and are not harmful to the eyes provided tha maintained in accordance with this User Man | reseeable conditions of operation t the products are used and ual. | |
| | Description | Value | |
| | Wavelength | 850 nm | |
| | Maximum average radiant power | 11 mW | |
| | Pulse duration | 20 ns, 40 ns | |
| | Pulse repetition frequency (PRF) | 24.4 kHz | |
| | Beam divergance | 0.4 mrad x 700 mrad | |



Electronic Guide Light (EGL)

General

1.6.7

The Electronic Guide Light built into the product produces a visible LED beam which emerges from the front side of the telescope.

The product described in this section, is excluded from the scope of IEC 60825-1 (2014-05): "Safety of laser products". The product described in this section, is classified as exempt group in accordance with IEC 62471 (2006-07) and does not pose any hazard provided that the product is used and maintained in accordance with this user manual.



1.6.8 Laser Plummet

General

The laser plummet built into the product produces a visible red laser beam which emerges from the bottom of the product.

The laser product described in this section is classified as laser class 2 in accordance with:

IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe for momentary exposures but can be hazardous for deliberate staring into the beam. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions.

| Description | Value |
|--|--|
| Wavelength | 640 nm |
| Maximum average radiant power | 0.95 mW |
| Pulse duration | 0.1 ms - cw |
| Pulse repetition frequency (PRF) | 1 kHz |
| Beam divergance | <1.5 mrad |
| Maximum average radiant power Pulse duration Pulse repetition frequency (PRF) Beam divergance | 0.95 mW 0.1 ms - cw 1 kHz <1.5 mrad |

Class 2 laser product

From a safety perspective, class 2 laser products are not inherently safe for the eyes.

Precautions:

- Avoid staring into the beam or viewing it through optical instruments.
- Avoid pointing the beam at other people or at animals.



Electromagnetic Compatibility (EMC)

Description

1.7

The term Electromagnetic Compatibility is taken to mean the capability of the product to function smoothly in an environment where electromagnetic radiation and electrostatic discharges are present, and without causing electromagnetic disturbances to other equipment.

Electromagnetic radiation

Electromagnetic radiation can cause disturbances in other equipment.

Precautions:

 Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment may be disturbed.

Use of the product with accessories from other manufacturers. For example field computers, personal computers or other electronic equipment, non-standard cables or external batteries

This may cause disturbances in other equipment.

Precautions:

- Use only the equipment and accessories recommended by Leica Geosystems.
- When combined with the product, they meet the strict requirements stipulated by the guidelines and standards.
- When using computers, two-way radios or other electronic equipment, pay attention to the information about electromagnetic compatibility provided by the manufacturer.

Intense electromagnetic radiation. For example, near radio transmitters, transponders, two-way radios or diesel generators

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that function of the product may be disturbed in such an electromagnetic environment.

Precautions:

• Check the plausibility of results obtained under these conditions.

Electromagnetic radiation due to improper connection of cables

If the product is operated with connecting cables attached at only one of their two ends, for example external supply cables, interface cables, the permitted level of electromagnetic radiation may be exceeded and the correct functioning of other products may be impaired.

Precautions:

While the product is in use, connecting cables, for example product to external battery, product to computer, must be connected at both ends.

Use of product with radio or digital cellular phone devices

Electromagnetic fields can cause disturbances in other equipment, in installations, in medical devices, for example pacemakers or hearing aids and in aircrafts. Electromagnetic fields can also affect humans and animals.

Precautions:

- Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment can be disturbed or that humans or animals can be affected.
- Do not operate the product with radio or digital cellular phone devices in the vicinity of filling stations or chemical installations, or in other areas where an explosion hazard exists.
- Do not operate the product with radio or digital cellular phone devices near to medical equipment.
- Do not operate the product with radio or digital cellular phone devices in aircrafts.
- Do not operate the product with radio or digital cellular phone devices for long periods with the product immediately next to your body.

FCC Statement, Applicable in U.S.

The greyed paragraph below is only applicable for products without radio.

1.8

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC rules.

These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Changes or modifications not expressly approved by Leica Geosystems for compliance could void the user's authority to operate the equipment.

Labelling TS13



Labelling internal battery GEB212, GEB222









WARNING

This Class (B) digital apparatus complies with Canadian ICES-003. Cet appareil numérique de la classe (B) est conforme à la norme NMB-003 du Canada.

Canada Compliance Statement

This device contains licence-exempt transmitter(s)/receiver(s) that comply with Innovation, Science and Economic Development Canada's licence-exempt RSS(s). Operation is subject to the following two conditions:

- 1. This device may not cause interference.
- 2. This device must accept any interference, including interference that may cause undesired operation of the device.

Canada Déclaration de Conformité

L'émetteur/récepteur exempt de licence contenu dans le présent appareil est conforme aux CNR d'Innovation, Sciences et Développement économique Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes:

- 1. L'appareil ne doit pas produire de brouillage;
- 2. L'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Description of the System

2 2.1

System Components

Main components



Terms and abbreviations

The following terms and abbreviations can be found in this manual:

| Term | Description | |
|----------------|--|--|
| Remote Mode | The instrument is remote controlled by the field controller or using radio. | |
| EDM | Electronic Distance Measurement | |
| | EDM refers to the laser distancer incorporated into the instrument which enables distance measurement. | |
| | Two measuring modes are available: Prism mode. This mode refers to the ability to measure distances to prisms. It incorporates the long range mode to measure extended distances to prisms. Any surface mode. This mode refers to the ability to measure distances without prisms. | |
| PinPoint | PinPoint refers to the Reflectorless EDM technology which enables an increased measuring range with a smaller laser spot size. Two options are available: R500 and R1000. | |
| EGL | Electronic Guide Light | |

| Term | Description | |
|----------------------------------|---|--|
| | An EGL fitted to an instrument assists with prism targeting. It consists of two differently coloured flashing lights located in the instrument telescope housing. The person holding the prism can align themselves into the line-of-sight of the instrument. | |
| Motorised | Instruments fitted with internal motors, enabling automatic horizontal and vertical turning are referred to as Motorised. | |
| ATR | Automatic Target Aiming. ATR refers to the instrument sensor which enables the auto- matic target aiming and locking. | |
| Automated | Instruments fitted with ATR are referred to as Automated. | |
| | ATR refers to the instrument sensor which enables the auto- matic target aiming to a prism. | |
| | Three automation modes are available with Aim at target:Manual: no automation and no lock.Automatic: automatic target aiming to a prism. | |
| Lock | Lock is an extension of ATR. An already targeted prism will be followed automatically. Optional. | |
| SpeedSearch | S peed S earch refers to the instrument sensor which enables the automatic rapid finding of a prism. Optional. | |
| SmartStation | A TS instrument integrated with an add-on GNSS system, comprising hardware and software components, forms a SmartStation. | |
| | Components of a SmartStation include a SmartAntenna and a SmartAntenna Adapter. | |
| | A SmartStation provides an additional instrument setup method for determining instrument station coordinates. | |
| | The GNSS principles and functionality of a SmartStation derive from the principles and functionality of Leica VivaGNSS instruments. | |
| SmartAn- tenna | SmartAntenna with integrated Bluetooth is a component of a SmartStation. It can also be used independently on a pole with a CS20 field controller. | |
| RadioHandle | A component of remote mode is the RH16/RH17 Radio- Handle. It is an instrument carry handle with an integrated long range Bluetooth module with attached antenna. The RadioHandle interface is only available if the Robotic option is purchased. | |
| Communica- tion side cover | Communication side cover with integrated Bluetooth, SD card slot, USB port and WLAN are standard for a TS13 instrument and a component of a SmartStation. In combina- tion with the RH16/RH17 RadioHandle, it is also a compon- ent of remote mode. The RadioHandle interface is only available if the Robotic option is purchased. | |

| Model | TS13 |
|---|--------------|
| Angle measurement | \checkmark |
| Distance measurement to prism | \checkmark |
| Distance measurement to any surface (reflectorless) | \checkmark |
| Motorised | \checkmark |
| Automatic Target Aiming | \checkmark |
| Lock | * |
| SpeedSearch | * |
| RS232, USB and SD card interface | \checkmark |
| Bluetooth | \checkmark |
| Internal Flash Memory (2 GB) | \checkmark |
| Hotshoe interface for RadioHandle | * |
| Guide Light (EGL) | \checkmark |
| WLAN | \checkmark |
| Keyboard Display Unit | * |
| | |

- ✓ Standard
- * Optional

2.2 System Concept

2.2.1

Software Concept

Description

| Туре | Firmware Upload | Application Upload |
|---------------------------------|--------------------|-----------------------|
| TS13 with four button keyboard | \checkmark | - |
| TS13 with keyboard display unit | \checkmark | \checkmark |

Software for TS models

| Software type | Description |
|--------------------------|---|
| TS firmware (xx.fw) | The Leica Captivate software is running on the TS instrument and covers all functions of the instrument. |
| | The main applications and languages are integrated into the firmware and cannot be deleted. |
| | The languages released with Leica Captivate are included in the firmware file. |
| Applications (xx.axx) | Many optional survey-specific applications are available for the TS instruments. All applications are included in the Leica Captiv- ate firmware file and can be loaded separ- ately. |
| | Some of the applications are activated freely and require no licence key; others require purchasing and are only activated with a licence key. |

| | Softw | vare type | Description |
|--------------------|----------------------|--|---|
| | | | If the licence is not loaded to the instru- ment, applications requiring a licence key run for a trial period. For a trial run, the Meas- ure&Stakeout licence must be available on the TS. |
| | Custor (xx.ax | mised applications x) | Customised software, specific to user requirements, can be developed using the GeoC++ development kit. Information on the GeoC++ development environment is avail- able on request from a Leica Geosystems representative. |
| Software upload | ð | Uploading software ca least 75% full before tery during the upload | an take some time. Ensure that the battery is at you start the upload. Do not remove the bat- I process. |
| | Softwa board | are update instruction without display: | s for instruments with a four button key- |
| | 1. | Download the most re https://myworld.leica- | ecent firmware file from geosystems.com. Refer to "Introduction". |
| | 2. | Copy the firmware file | into the System folder on the Leica SD card. |
| | 3. | Start the instrument. | |
| | 4. | The upload process st The Power LED of the green when the firmw The firmware file is rer | arts automatically. keyboard unit is red during the upload and are update is finished. named with a suffix "installed". |
| | Softwa with d | are update instruction isplay: | s for instruments with a full keyboard and |
| | 1. | Download the most re https://myworld.leica- | ecent firmware file from geosystems.com. Refer to "Introduction". |
| | 2. | Copy the firmware file | into the System folder on the Leica SD card. |
| | 3. | Start the instrument. Select the firmware file | Select Settings\Tools\Update software . e and start the update. |
| | 4. | When the update is co | omplete, a message appears. |
| Licence activation | For ins | struments with a Four | Button Keyboard Unit |
| | B | Licences are key code | s to enable software functions and applica- |
| | | tions which run on the You can order new lice service partner. | e instrument. ences on myWorld or by contacting your local |
| | 1. | tions which run on the You can order new lice service partner. Store the licence key to card. | e instrument. ences on myWorld or by contacting your local file (*.key) in the \SYSTEM folder of the SD |
| | 1. | tions which run on the You can order new lice service partner. Store the licence key to card. Insert the SD card into Memory Device". | e instrument. ences on myWorld or by contacting your local file (*.key) in the \SYSTEM folder of the SD o the TS13. Refer to "4.7 Working with the |
| | 1. 2. 3. | tions which run on the You can order new lice service partner. Store the licence key to card. Insert the SD card into Memory Device". Turn on the TS13. | e instrument. ences on myWorld or by contacting your local file (*.key) in the \SYSTEM folder of the SD o the TS13. Refer to "4.7 Working with the |

5. After successful loading, the licence key file is renamed with the suffix "..._loaded".

| If the software maintenance licence has expired: Contact your local service partner to update the software on the product. |
|--|
| If the licence activation fails: |
| Contact your local service partner or create a new support request |

For instruments with a Keyboard Display Unit

on myWorld.

Refer to the Captivate Technical Reference Manual for information about the license upload.

| 2.2.2 | Power Concept | | | |
|---------------|--|---|--|--|
| General | Use the batteries, chargers and accessories recommended by Leica Geosys- tems to ensure the correct functionality of the instrument. | | | |
| Power options | Model | Power supply | | |
| | all TS models | Internally by GEB222 battery, OR | | |
| | | Externally by GEV52 cable and GEB371 battery. | | |
| | | If an external power supply is connected and the internal battery is inserted, then the external power is used. | | |
| | SmartAn- tenna | Internally via GEB212 battery fitted into the antenna. | | |
| 2.2.3 | Data Storag | e Concept | | |
| Description | For instruments with a four button keyboard without display: | | | |
| | Data storage is only possible on the connected controller. On a CS20, the available memory devices are an SD card and an internal memory. | | | |
| | For instruments with a keyboard display unit: | | | |
| | Data is stored on a TS memory device. The memory device can be an SD card or internal memory. For data transfer an USB stick can also be used. | | | |
| Memory device | Device | Description | | |
| | SD card | All instruments have an SD card slot fitted as standard. An SD card can be inserted and removed. Available capacity: 1 GB and 8 GB. | | |
| | USB stick | All instruments have a USB port fitted as standard. | | |
| | Internal memory | All instruments have an internal memory fitted as standard. Available capacity: 2 GB. | | |
| | While other SD cards/USB sticks can be used, Leica Geosystems recommends to only use Leica SD cards/USB sticks and is not responsible for data loss or any other error that can occur while using a non-Leica SD card/USB stick. | | | |

Unplugging connecting cables or removing the SD card or USB stick during the measurement can cause loss of data. Only remove the SD card or USB stick or unplug connecting cables when the TS instrument is switched off.

Transfer data

F

2.3

F

Data can be transferred in various ways.

SD cards can directly be used in an OMNI drive as supplied by Leica Geosystems. Other PC card drives can require an adaptor.

Container Contents

Container for instrument and accessories part 1 of 2



0016274_001

- a Stylus
- b GLS14 mini pole
- c GHM007 Instrument height meter
- d Allen key and adjustment tool
- e Tip for GMP101 mini prism
- f Instrument with tribrach and standard handle or RadioHandle
- g GMP101 mini prism
- h GEB222 batteries
- i GFZ3 or GOK6 diagonal eyepiece
- j Counterweight for diagonal eyepiece
- k MS1, 1 GB USB memory stick
- I GEV192 AC power supply for battery charger
- m GRZ4 or GRZ122 prism
- n Manuals and USB documentation card

Container for instrument and accessories part 2 of 2



a Cable

- Cables GHT196 tribrach bracket for height meter
- b GHT196 tribrach brackec SD cards and covers
- d GKL311 battery charger
- e Car adapter power plug for battery charger (stored under battery charger)
- f Protective cover for instrument, sunshade for objective lens and cleaning cloth

Container for TS robotic pole setup, Small-Size



- a Manuals and USB documentation card
- b GAT25 radio antenna
- c Mini prism spike
- d GRZ4 or GRZ122 prism
- e SD card and cover
- f Adjustment tool and allen key
- g GRZ101 mini prism and GAD103 adapter
- h GEB331 battery
- i GHT63 pole holder clamp
- j Tip for mini pole
- k GLI115 clip-on bubble for GLS115 mini prism pole
- I CS20 field controller and GHT66 holder
- m Stylus

2.4

Instrument components part 1 of 2

Instrument Components



- a Carry handle
- b Optical sight
- c Telescope with integrated EDM, ATR, EGL, SpeedSearch*
- d EGL flashing diode yellow and red
- e SpeedSearch, transmitter
- f SpeedSearch, receiver
- g Coaxial optics for angle and distance measurement, and exit port of visible laser beam for distance measurements
- h SD Card and USB stick
- i Loudspeaker
- j Horizontal drive
- k Tribrach footscrew
- I Tribrach securing screw

* optional

Instrument components part 2 of 2



- a Vertical drive
- b Focusing ring
- c Interchangeable eyepiece
- d Circular level
- e Battery compartment
- f Four button keyboard unit
- g Keyboard display unit*

* optional

Communication Side Cover



- Compartment lid а
- Ь
- USB stick cap storage USB device port (mini AB OTG) С
- USB host port for USB stick d
- SD card port е

Instrument components for SmartStation



- GS14/GS16 SmartAntenna а
- Ь GAD110 SmartAntenna Adapter
- Communication side cover С

Instrument components for remote mode



| 3 | User Interface | |
|-------------|---|--|
| 3.1 | Keyboard | |
| Description | The TS13 basic variant has a four button keyboard unit without display. The basic variant can be upgraded with a keyboard display unit. Both variants can be upgraded with purchased options that enable Lock, SpeedSearch and the RadioHandle interface on the instrument. | |

Four Button Keyboard Unit

Four button keyboard without display

3.1.1

| a b | cd | efgh | |
|------|--------|-----------|---|
| ì | | | 6 |
| n_ | _ | (\circ) | 1 |
| LOCK | (MEAS) | CON) | |
| 0 | 0 | 0 | |
| 1 ke | Lenn | | |
| 1 | | | 0 |

- a LOCK key
- b LED for locking status
- c MEAS key
- d LED for measurement status
- e LED for communication status
- f LED for power status
- g ON/OFF key
- h COM key

TS13 key functions and LED behaviour

The following description of key functions and LED behaviours applies to the TS13 being connected to a field controller.

| Key func | tions | |
|----------------|--|--|
| LOCK | Press to start prism search and lock onto prism.If already locked: Press to unlock from prism. | |
| MEAS | Depending on the currently active settings and field control- ler application: Press to start a measurement or to store a measurement. | |
| ON/OFF | Press for 2 s to turn on the instrument. Press and hold for more than 2 s to shut down the instrument. Press and hold for more than 5 s to reset the sensor. Press and hold for more than 8 s to do a hard shutdown. | |
| COM | To toggle through the communication modes, press the key repeatedly. Communication modes: RS232 Bluetooth Long-range Bluetooth Press and hold for more than 5 s to change between CS controller and Geocom connection. | |
| LED behaviours | | |
| LOCK | Off: Prism not locked.Solid green: Prism found and locked. | |
| MEAS | Off: No active measurement. | |

| LED behaviours | | | | |
|--------------------------------------|--|--|--|--|
| ON/OFF | Off: Instrument is switched off. Solid red after switching on: Instrument is booting. Solid green/yellow/red: Indicator for the battery status. Green: More than 40% of battery charge remaining. Yellow: More than 20% of battery charge remaining. Red: Remaining battery charge is very low. Flashing green: Instrument is shutting down. | | | |
| COM | Off: RS232 Serial port selected. Solid green: Internal Bluetooth selected. Solid red: Long-range Bluetooth using RadioHandle is selected. Solid blue: Bluetooth communication established to CS controller using Internal Bluetooth or long-range Bluetooth. | | | |
| LOCK, MEAS and COM together | Solid green/red: Changing between CS controller and Geo- com connection. Solid red: Reset process of the system is started. | | | |

3.1.2

Keyboard display unit

Keyboard Display Unit



- Display а Alphanumeric keys Ь
- ON/OFF С
- Backspace d
- Favourites e
- f Home
- g h Esc
- Fn i.
 - ОК
- Arrow keys j k
 - Enter
- Camera* L
- * Not applicable

Keys

| Кеу | | Function | |
|----------------------|----------------------|--|--|
| Alphanumeric keys | ані • 4 с. | To type letters and numbers. | |
| Esc | 日の | Leaves the current screen without storing any changes. | |
| Fn | $Fn \omega$ | Switches between first and second level of any key on the keyboard. | |
| Enter | () 🛶 | Selects the highlighted line and leads to the next logical menu / dialog. | |
| | | Starts the edit mode for editable fields. | |
| | | Opens a selectable list. | |
| ON/OFF | 5 C | If the instrument is already off: Turns on the instrument when held for 2 s. | |

| Кеу | | Function |
|-------------|----------------|---|
| | | If the instrument is already on: Turns to Power Options menu when held for 2 s. |
| Favourites | *** | Goes to a favourites menu. |
| Home | e) † | Switches to the Home Menu. |
| Arrow keys | | Move the focus on the screen. |
| ОК | OK | Selects the highlighted line and leads to the next logical menu / dialog. |
| | | Starts the edit mode for editable fields. |
| | | Opens a selectable list. |
| Backspace | *** | Deletes the job in the centre of the job carousel. |
| | | |
| Кеу | | Function |
| Fn ex | 50 | Hold Fn while pressing <u>57</u> . Switch to Windows. |
| + Fn (-) | () () () | Hold Fn while pressing 📶. Take a screenshot of the current screen. |
| + Fn (-) | .10 | Hold Fn while pressing 1 . Increase the screen brightness. |
| + Fn ⊙ | GHI *4 (~) | Hold Fn while pressing 4 . Decrease the screen brightness. |
| Fn (·) | DEF Q. | Hold Fn while pressing 3 . Increase the volume for acoustic warning signals, beeps and keypresses on the instru- ment. |
| Fn Θ | мио «Ц | Hold Fn while pressing 6 . Decrease the volume for acoustic warning signals, beeps and keypresses on the instru- ment. |
| + Fn (-) | PORS 7() | Hold Fn while pressing 7 . Lock/unlock the keyboard. |
| + Fn (-) | WXYZ | Hold Fn while pressing 9 . Lock/unlock the touch screen. |
| Fn 😔 | + | Hold Fn while pressing E . Enter a plus sign instead of a minus sign. |
| Fn (e) | #_/ 追 • () | Hold Fn while pressing |
| | | |

Key combinations

| 3.2 | Operating Principles Refer to Four Button Keyboard Unit for the operating principles of the four button keyboard. | | | |
|---------------------------|---|--|--|--|
| | | | | |
| Keyboard and touch screen | The user interface is operated either by the keyboard or by the touch screen with supplied stylus. The workflow is the same for keyboard and touch screen entry, the only difference lies in the way information is selected and entered. | | | |
| | Operation by keyboard | | | |
| | Information is selected and entered using the keys. | | | |
| | Operation by touch screen | | | |
| | Information is selected and entered on the screen using the supplied stylus. | | | |
| | Operation | Description | | |
| | To select an item | Tap on the item. | | |
| | To start the edit mode in editable fields | Tap on the editable field. | | |
| | To highlight an item or parts of it for editing | Drag the supplied stylus from the left to the right. | | |
| | To accept data entered into an edit- able field and exit the edit mode | Tap on the screen outside of the editable field. | | |
| | To open a context-sensitive menu | Tap on the item and hold for 2 s. | | |
| 4 | Operation | | |
|---|---|--|--|
| 4.1 | Setting Up the TS Instrument | | |
| 4.1 Instrument setup step-by-step | \mathbf{N} | | |
| | 0016251_001 | | |
| | Shield the instrument from direct sunlight and avoid uneven temper atures around the instrument. | | |
| | 1. Extend the tripod legs to allow for a comfortable working posture. Position the tripod above the marked ground point, centring it as good as possible. Ensure that the tripod plate is roughly horizontal. | | |
| | 2. Fasten the tribrach and instrument onto the tripod. | | |
| | 3. Turn on the instrument by pressing and. Select Settings/TS instru- ment/Level & compensator to activate the laser plummet and electronic level. | | |
| | 4. Use the tribrach footscrews (a) to centre the plummet (b) above the ground point. | | |
| | 5. Adjust the tripod legs to level the circular level (c). | | |
| | 6. By using the electronic level, turn the tribrach footscrews (a) to leve the instrument precisely. | | |
| | 7. Centre the instrument precisely over the ground point (b) by shifting the tribrach on the tripod plate. | | |
| | 8. Repeat steps 6. and 7. until the required accuracy is achieved. | | |
| 4.2 | Setting up for Remote Control (with the RadioHandle) | | |
| Availability | For this functionality, the TS13 Robotic licence must be purchased. | | |

Attaching the Radio-Handle step-by-step



- Refer to "4.1 Setting Up the TS Instrument" for the initial instrument setup onto a tripod.
- 1. To remove the instrument carry handle: Press and hold the four unlock push buttons and lift off the handle.
- 2. To install the RadioHandle, first make sure that the interface connection on the lower part of the handle is on the same side as the Communication side cover. Then press and hold the four unlock push buttons and attach the handle.
- Ensure that there is a tight fit with the instrument after releasing the push buttons. If no connection can be found, re-check that handle is seated firmly.
- 3. Swing the antenna of the RadioHandle into an upright position.

Setup for remote control with RadioHandle



Fixing the Field Controller to a Holder and Pole

Components of the GHT66 holder

The GHT66 holder consists of the following components:



Fixing the field controller and GHT66 to a pole step-bystep

| 3 | For an aluminium pole, fit the plastic sleeve to the pole clamp. |
|----|--|
| 1. | Insert the pole into the clamp hole. |
| 2. | Attach the holder to the clamp using the clamp bolt. |
| 3. | Adjust the angle and the height of the holder on the pole to a com- fortable position. |
| 4. | Tighten the clamp with the clamp bolt. |
| 5. | Before placing the CS field controller onto the mounting plate, ensure that the locking pin is put into the unlocked position. To |





- 6. Hold the CS field controller above the holder and lower the end of the CS field controller into the mounting plate.
- 7. Apply slight pressure in a downward direction and then lower the top part of the CS field controller until the unit is clicked into the holder. The guides of the mounting plate aid in this action.



8. After the CS field controller is placed onto the mounting plate, ensure that the locking pin is put into the locked position. To lock the locking pin, push the locking pin to the right.



Detaching the field controller from a pole step-by-step

4.4

- 1. Unlock the locking pin by pushing the locking pin to the left of the mounting plate.
- 2. Place your palm over the top of the field controller.
- 3. While in this position, lift the top of the field controller from the holder.



Connecting to a Personal Computer

| Description | Windows Mobile Device Center for PC with Windows 7/Windows 8/Windows 10 operating system is the synchronization software for Windows mobile-based pocket PC. WMDC enables a PC and a Windows mobile-based pocket PC to communicate. | | | |
|-----------------------------------|---|--|--|--|
| | Leica USB drivers support Windows 7, Windows 8 (8.1) and Windows 10 oper- ating systems. | | | |
| | Cables | | | |
| | Leica U | SB drivers support: | | |
| | Name | Description | | |
| | GEV22 | 3 USB data cable, 1.8 m, connects instrument to Mini-USB to USB | | |
| | GEV23 | 4 USB data cable, 1.65 m, connects CS to GS or CS to PC (USB) | | |
| | GEV26 | 1 Y-cable, 1.8 m, connects instrument to PC – battery | | |
| Uninstalling the previous drivers | ß | Skip the following steps if you have never installed Leica USB drivers before. | | |
| | If older drivers were previously installed on the PC, follow the instructions to uninstall the drivers prior the installation of the new drivers. | | | |
| | 1. | Connect your instrument to the PC via cable. | | |
| | 2. On your PC, select to Control Panel > Device Manager . | | | |
| | | | | |

| | 3. | In Network Adapters, right-click on Remote NDIS based LGS | | | | | |
|-------------------|----|--|--|--|--|--|--|
| | 4. | Click on Uninstall . | | | | | |
| | | Microsoft Virtual WiFi Miniport Adapter Remote NDIS based LGS CS Device #2 | | | | | |
| | | Other devices Update Driver Software Ports (COM & LPT) Disable | | | | | |
| | | Processors Uninstall | | | | | |
| | | Sound, video and game controlle Scan for hardware changes | | | | | |
| | | Image: properties Properties | | | | | |
| | 5. | Set Delete the driver as checked. Press OK . | | | | | |
| | | Confirm Device Uninstall | | | | | |
| | | Remote NDIS based LGS CS Device #2 | | | | | |
| | | | | | | | |
| | | Warning: You are about to uninstall this device from your system. | | | | | |
| | | Delete the driver software for this device. | | | | | |
| | | | | | | | |
| | | OK Cancel | | | | | |
| | | | | | | | |
| Install Leica USB | 1. | Start the PC. | | | | | |
| unvers | 2. | 2. Run the Setup_Leica_USB_XXbit.exe to install the drivers necessary | | | | | |
| | | operating system on your PC, you have to select between the three | | | | | |
| | | setup files following: | | | | | |
| | | Setup_Leica_USB_32bit.exe | | | | | |
| | | Setup_Leica_USB_64bit.exe Setup_Leica_USB_64bit.itanium.exe | | | | | |
| | | To check the version of your operating system, go to | | | | | |
| | | Control Panel > System > System type. | | | | | |
| | | The setup requires administrative privileges. | | | | | |
| | | The setup has to be run only once for all Leica devices. | | | | | |
| | 3. | The Welcome to InstallShield Wizard for Leica GS, TS/TM/MS, CS and GR USB drivers window appears. | | | | | |
| | | Ensure that all Leica devices are disconnected from your PC before you continue! | | | | | |



| A file browser opens. | You ca | n now | browse | within | the | folders | on t | he |
|-----------------------|--------|-------|--------|--------|-----|---------|------|----|
| instrument. | | | | | | | | |

| 4.5 Power Functions | | | | |
|---------------------------------------|--|---|------------------------------------|---|
| Power functions | Option | Кеу | Descri | ption |
| | Turn on | ON/OFF | Press a | and hold for 2 s. The instrument must have a power supply. |
| | Turn off | ON/OFF | Press a | and hold for 2 s. For instruments set up in perman- ent installations with external power sources, for example monit- oring, ensure external power remains available until the instru- ment has successfully completed the power down process. |
| | Reset | ON/OFF | Press a Parts o | and hold for more than 5 s. of the internal memory are reset. |
| | Hard shutdown | ON/OFF | Press a | and hold for more than 8 s. |
| 4.6 | Batteries | | | |
| 4.6.1 | Operating Principles | | | |
| First-time use/ charging batteries | The battery must be charged before using it for the first time because it is delivered with an energy content as low as possible. The permissible temperature range for charging is from 0 °C to +40 °C/+32 °F to +104 °F. For optimal charging, we recommend charging the batteries at a low ambient temperature of +10 °C to +20 °C/+50 °F to +68 °F if possible. It is normal for the battery to become warm during charging. Using the chargers recommended by Leica Geosystems, it is not possible to charge the battery once the temperature is too high. For new batteries or batteries that have been stored for a long time (> three months), it is effectual to make only one charge/discharge cycle. For Li-lon batteries, a single discharging and charging cycle is sufficient. We recommend carrying out the process when the battery capacity indicated on the charger or on a Leica Geosystems product deviates significantly from the actual battery capacity available. | | | |
| Operation/ discharging | The batter Low operating | ies can be opera ting temperature temperatures re | ated from es reduce duce the | n –20 °C to +55 °C/–4 °F to +131 °F. e the capacity that can be drawn; high service life of the battery. |

Battery for the TS Instrument

Change battery stepby-step



- 4. At the top of the battery is a notch which corresponds to the inner surface of the battery housing. This notch helps you to place the battery correctly.
- 5. Place the battery into the battery housing, ensuring that the contacts are facing outward. Click the battery into position.
- 6. Place the battery housing into the battery compartment. Push the battery housing in until it fits completely into the battery compartment.
- 7. Turn the knob to lock the battery compartment. Ensure that the knob is returned to its original horizontal position.

| 4.7 | Working with the Memory Device |
|-------|---|
| | Keep the card dry. Use it only within the specified temperature range. Do not bend the card. Protect the card from direct impacts. |
| 3 | Failure to follow these instructions could result in data loss and/or permanent damage to the card. |
| - All | The TS13 with the four button keyboard and without display uses the memor- ies only for firmware/license key upload. |

4.6.2

Insert and remove an SD card step-by-step



- The SD card is inserted into a slot inside the Communication side cover of the instrument.
- 1. Turn the knob on the Communication side cover to the vertical position to unlock the communication compartment.
- 2. Open the lid of the communication compartment to access the communication ports.
- 3. To insert the SD card, slide it firmly into the SD slot until it clicks into position.
 - The card must be held with the contacts at the top and facing toward the instrument.
 - Do not force the card into the slot.
- 4. Close the lid and turn the knob to the horizontal position to lock the communication compartment.
- 5. To remove the SD card, gently press on the top of the card to release it from the slot.

Insert and remove a USB stick step-bystep



- The USB stick is inserted into the USB host port inside the Communication side cover of the instrument.
- Turn the knob on the Communication side cover to the vertical position to unlock the communication compartment.
 Open the lid of the communication compartment to access the com-
- munication ports.3. Slide the USB stick with the Leica logo facing you firmly into the USB
- 3. Slide the USB stick with the Leica logo facing you firmly into the USB host port until it clicks into position.

| | Do not force the USB stick into the port. |
|----|--|
| 4. | If desired, store the lid of the USB stick on the underside of the compartment lid. |
| 5. | Close the lid and turn the knob to the horizontal position to lock the compartment. |
| 6. | To remove the USB stick, open the lid of the compartment and slide the USB stick out of the port. |

4.8 **LED Indicators**

LED indicators on RadioHandle

Description

The RadioHandle has ${\bf L}$ ight ${\bf E}$ mitting ${\bf D}$ iode indicators. They indicate the basic RadioHandle status.

Diagram of the LED Indicators



- Power LED а
- Ь Link LED
- Data Transfer LED С
- d Mode LED

Description of the LED Indicators

| IF the | is | THEN |
|---------------|-------------------------------|--|
| Power LED | off | power is off. |
| | green | power is on. |
| Link LED | off | no radio link to field controller. |
| | red | radio link to field controller. |
| Data Transfer | off | no data transfer to/from field controller. |
| LED | green or green flashing | data transfer to/from field controller. |
| Mode LED | off | data mode. |
| | red | configuration mode. |

Guidelines for Correct Results

Distance measurement

| 002410.002 | |
|------------|--|

When measurements are being made using the red laser EDM, the results can be influenced by objects passing between the EDM and the intended target surface. This occurs because reflectorless measurements are made to the first surface returning sufficient energy to allow the measurement to take place. For example, if the intended target surface is the surface of a building, but a vehicle passes between the EDM and the target surface as the measurement is triggered, the measurement may be made to the side of the vehicle. The result is the distance to the vehicle, not to the surface of the building.

If using the long range measurement mode (> 1000 m, > 3300 ft) to prisms, and an object passes within 30 m of the EDM as the measurement is triggered, the distance measurement may be similarly effected due to the strength of the laser signal.

Very short distances can also be measured reflectorless in **Prism** mode to well reflecting natural targets. The distances are corrected with the additive constant defined for the active reflector.

AWARNING

Due to laser safety regulations and measuring accuracy, using the Long Range Reflectorless EDM is only allowed to prisms that are more than 1000m (3300ft) away.

Accurate measurements to prisms should be made in **Prism** mode.

When a distance measurement is triggered, the EDM measures to the object which is in the beam path at that moment. If a temporary obstruction, for example a passing vehicle, heavy rain, fog or snow is between the instrument and the point to be measured, the EDM may measure to the obstruction.

Do not measure with two instruments to the same target simultaneously to avoid getting mixed return signals.

ATR/Lock Instruments equipped with an ATR sensor permit automatic angle and distance measurements to prisms. The prism is sighted with the optical sight. After initiating a distance measurement, the instrument sights the prism centre automatically. Vertical and horizontal angles and the distance are measured to the centre of the prism. The lock mode enables the instrument to follow a moving prism.

4.9

-3

F

3

F

| | As with all other instrument errors, the collimation error of the automatic aim- ing must be redetermined periodically. Refer to "5 Check & Adjust" about checking and adjusting instruments. |
|--------|---|
| 23 | When a measurement is triggered while the prism is still moving, distance and angle measurements may not be made for the same position and coordinates may vary. |
| - | If the prism location is changed too quickly, the target may be lost. Make sure that the speed does not exceed the figure given in the technical data. |

| 5 | Check & Adjust | | | |
|--------------------------|--|---|--|--|
| 5.1 | Overview | | | |
| Description | Leica Geosystems instruments are manufactured, assembled and adjusted to the best possible quality. Quick temperature changes, shock or stress can cause deviations and decrease the instrument accuracy. It is therefore recom- mended to check and adjust the instrument from time to time. This check and adjust can be done in the field by running through specific measurement pro- cedures. The procedures are guided and must be followed carefully and pre- cisely as described in the following chapters. Some other instrument errors and mechanical parts can be adjusted mechanically. | | | |
| 1. Jan | For a TS13 basic variant, | , Check & Adjust must be done remotely using a CS20. | | |
| Electronic adjustment | The following instrumen | t errors can be checked and adjusted electronically: | | |
| | Instrument error | Description | | |
| | l, t | Compensator longitudinal and transversal index errors | | |
| | i | Vertical index error, related to the standing axis | | |
| | С | Horizontal collimation error, also called line of sight error | | |
| | а | Tilting axis error | | |
| | ATR | ATR zero point error for Hz and V | | |
| | If the compensator and the horizontal corrections are activated in the instru- ment configuration, every angle measured in the daily work is corrected auto- matically. Check whether the tilt correction and the horizontal correction are turned on. | | | |
| | The results are displayed as errors but used with the opposite sign as correc- tions when applied to measurements. | | | |
| Mechanical adjustment | The following instrument parts can be adjusted mechanically: Circular level on instrument and tribrach Optical plummet - option on tribrach Allen screws on tripod | | | |
| Precise measurements | To get precise measurements in the daily work, it is important: To check and adjust the instrument from time to time. To take high precision measurements during the check and adjust produres. To measure targets in two faces. Some of the instrument errors are el inated by averaging the angles from both faces. | | | |

During the manufacturing process, the instrument errors are carefully determined and set to zero. As mentioned above, these errors can change and it is highly recommended to redetermine them in the following situations:

- Before the first use
- Before every high precision survey
- After rough or long transportation
- After long working periods
- After long storage periods
- If the temperature difference between current environment and the temperature at the last calibration is more than 20 °C

| Summary of errors to be adjusted electronically | Instrument error | Effects Hz | Effects V | Elimination with two face measurement | Automatically corrected with proper adjustment |
|---|--------------------------------|---------------|--------------|---|---|
| | c - Line of sight error | \checkmark | - | \checkmark | \checkmark |
| | a - Tilting axis error | \checkmark | _ | ✓ | ✓ |
| | l - Compensator index error | _ | \checkmark | √ | ✓ |
| | t - Compensator index error | \checkmark | - | √ | ✓ |
| | i - Vertical index error | _ | \checkmark | \checkmark | \checkmark |
| | ATR Collimation error | \checkmark | \checkmark | - | ✓ |

Preparation

F

5.2



Before determining the instrument errors, the instrument has to be levelled using the electronic level.

The tribrach, the tripod and the underground should be stable and secure from vibrations or other disturbances.

B



The instrument should be protected from direct sunlight to avoid thermal warming.

It is also recommended to avoid strong heat shimmer and air turbulence. The best conditions are early in the morning or with overcast sky.

B

1-2

Before starting to work, the instrument has to become acclimatised to the ambient temperature. Take at least 15 minutes into account or approximately 2 minutes per °C of temperature difference from storage to working environment.

Even after adjustment of the ATR, the crosshairs may not be positioned exactly on the centre of the prism after an ATR measurement has been completed. This outcome is a normal effect. To speed up the ATR measurement, the telescope is normally not positioned exactly on the centre of the prism. These small deviations ATR offsets, are calculated individually for each measurement and corrected electronically. This means that the horizontal and vertical angles are corrected twice: first by the determined ATR errors for Hz and V, and then by the individual small deviations of the current aiming.

Next step

| IF the task is to | THEN |
|---|---|
| adjust a combination of instrument errors | Refer to "5.3 Combined Adjustment (I, t, i, c and ATR)". |
| adjust the tilting axis | Refer to "5.4 Tilting Axis Adjustment (a)". |
| adjust the circular level | Refer to "5.5 Adjusting the Circular Level of the Instrument and Tribrach". |
| adjust the laser/optical plum- met | Refer to "5.7 Inspecting the Laser Plummet of the Instrument". |
| adjust the tripod | Refer to "5.8 Servicing the Tripod". |

5.3

Combined Adjustment (I, t, i, c and ATR)

Description

The combined adjustment procedure determines the following instrument errors in one process:

| | Instrument error | Description |
|--|---------------------|---|
| | l, t | Compensator longitudinal and transversal index errors |
| | i | Vertical index error, related to the standing axis |
| | С | Horizontal collimation error, also called line of sight error |
| | ATR Hz | ATR zero point error for horizontal angle option |
| | ATR V | ATR zero point error for vertical angle option |
| Combined adjustment procedure step-by- | The following table | e explains the most common settings. |
| step | | Divate - Home. Settings/15 instrument/check & aujust |

| 1. | Leica Captivate - Home: Settings\TS instrument\Check & a |
|----|---|
| 2. | Check & Adjust |
| | Colored the protions. Charals C. a direct the proven expectant index. |

Select the option: Check & adjust the compensator, index error, line of sight error & automatic target aiming

3. Next

4. Face I measurement



| 11. | Select Finish to accept the results. No more runs can be added |
|-----|--|
| | later. |

OR

Select ${\bf Redo}$ to decline all measurements and to repeat all calibration runs.

OR

Back returns to the previous screen.

| — | | |
|---|--|---|
| Next step | IF the results are | THEN |
| | to be stored | If the Use status is set to Yes, Next over- writes the old adjustment errors with the new ones. |
| | to be determined again | Redo rejects all new determined adjustment errors and repeats the whole procedure. Refer to paragraph "Combined adjustment procedure step-by-step". |
| 5.4 | Tilting Axis Adjustme | ent (a) |
| Description | This adjustment procedure | determines the following instrument error: |
| | Instrument error | Description |
| | а | Tilting-axis error |
| - | | |
| Determination of tilt- ing axis error step-by- | The following table explains | s the most common settings. |
| step | Determine the hole procedure. | rizontal collimation error (c) before starting this |
| | 1. Leica Captivate - | Home: Settings TS instrument Check & adjust |
| | 2. Check & Adjust | |
| | Select the option: | Check & adjust the tilting axis |
| | 3. Face I measurem Aim the telescope a target at about tance (or at least target must be po least 27°/30 gon a beneath the horiz The procedure car any telescope face | nent accurately at 100 m dis- 20 m). The sitioned at above or ontal plane. n be started in e. -27° |

- 4. **Measure** to measure and to continue to the next screen. Motorised instruments change automatically to the other face. Non-motorised instruments guide to the other face.
 - The fine pointing must be performed manually in both faces.



| 5. | Face II measureme | nt | | |
|--------|--|--|--|--|
| | Measure to measur culate the tilting axi | e the same target in the other face and to cal- s error. | | |
| 13 | If the error is bigger be repeated. The till then rejected and n | than the predefined limit, the procedure must ting axis measurements of the current run are ot averaged with the results from previous runs. | | |
| 6. | Adjustment Status | | | |
| | Number of measure One run consists of | rements : Shows the number of runs completed. a measurement in face I and face II. | | |
| | a T-axis quality (1 ined tilting axis erro the second run onw | σ): shows the standard deviation of the determ- r. The standard deviation can be calculated from ards. | | |
| B | Measure at least two | o runs. | | |
| 7. | Next to continue wi | th the check & adjust procedure. | | |
| 8. | Select Add another added. Next and co | Select Add another calibration loop if more runs have to be added. Next and continue with step 3. | | |
| | OR | | | |
| | Select Finish the ca ibration process. No adjustment results. | alibration & store the results to finish the cal- more runs can be added later. Next to view the | | |
| 9. | Select Finish to acc later. | ept the results. No more runs can be added | | |
| | OR | | | |
| | Select Redo to decli tion runs. | ine all measurements and to repeat all calibra- | | |
| IF the | e results are | THEN | | |
| to be | stored | Next overwrites the old tilting axis error with the new one. | | |
| to be | determined again | Redo rejects the new determined tilting axis error and repeats the whole procedure. Refer to paragraph "Determination of tilting | | |

axis error step-by-step".

Next step

Adjusting the Circular Level of the Instrument and Tribrach

5.5

Adjusting the circular level step-by-step



| 1. | Place and secure the instrument into the tribrach and onto a tripod. | | |
|--------|--|---|--|
| 2. | Using the tribrach footscrews, level the instrument with the elec- tronic level. | | |
| 3. | Select Settings\TS instrument\Level & compensator to access the Level & Compensator panel. | | |
| 4. | Check the position of the circular level on the instrument and tri- brach. | | |
| 5. | а | If both circular levels are centred, no adjustments are neces- sary | |
| | b | If one or both circular levels are not centred, adjust as fol- lows: | |
| | In ke by lai | strument : If it extends beyond the circle, use the supplied allen ey to centre it with the adjustment screws. Turn the instrument v 200 gon (180°). Repeat the adjustment procedure if the circu- r level does not stay centred. | |
| | Tr ke | ibrach : If it extends beyond the circle, use the supplied allen by to centre it with the adjustment screws. | |
| - B | Afte tigh | r the adjustments, all adjusting screws must have the same tening tension and no adjusting screw should be loose. | |

| 5.6 | Adjus | sting the Circular Level of the Prism Pole | |
|------------------------|-------|--|---------------------------|
| Adjusting the circular | 1. | Suspend a plumb line. | ~ 8 1 |
| level step-by-step | 2. | Use a pole bipod, to align the prism pole parallel to the plumb line. | 4b |
| | 3. | Check the position of the circular level on the prism pole. | |
| | 4. | a If the circular level is centred, no adjustment is necessary. | 2 |
| | | b If the circular level is not centred, use an allen key to centre it with the adjustment screws. | |
| | ß | After the adjustments, all adjusting screws must hat tightening tension and no adjusting screw should t | ave the same be loose. |

Inspecting the Laser Plummet of the Instrument

The laser plummet is located in the vertical axis of the instrument. Under normal conditions of use, the laser plummet does not need adjusting. If an adjustment is necessary due to external influences, return the instrument to any Leica Geosystems authorised service workshop.

Inspecting the laser plummet step-by-step

5.7

F



The following table explains the most common settings.

- 1. Set up the instrument on the tripod approximately 1.5 m above the ground and level up.
- Select Settings\TS instrument\Level & compensator to access the Level & Compensator panel. The laser plummet is switched on when the Level & Compensator panel is entered. Adjust the laser plummet intensity.
 - Inspection of the laser plummet should be carried out on a bright, smooth and horizontal surface, such as a sheet of paper.
- 3. Mark the centre of the red laser dot on the ground.

- 4. Turn the instrument slowly through 360°, carefully observing the movement of the red laser dot.
 - The maximum diameter of the circular movement described by the centre of the laser dot should not exceed 3mm at a height of 1.5m.
- 5. If the centre of the laser dot describes a perceptible circular movement, or moves more than 3 mm away from the point which was first marked, an adjustment may be required. Inform your nearest Leica Geosystems authorised service centre. Depending on brightness and surface, the diameter of the laser dot can vary. At 1.5 m, it is about 2.5 mm.

Servicing the Tripod

Servicing the tripod step-by-step

5.8



The following table explains the most common settings.

| (b) | The connections between metal and timber components must always be firm and tight. |
|-----|---|
| 1. | Tighten the leg cap screws moderately, with the supplied Allen key. |
| 2. | Tighten the articulated joints on the tripod head enough to keep the tripod legs open when lifting the tripod off the ground. |
| 3. | Tighten the Allen screws of the tripod legs. |

| 6 | Care and Transport |
|--|--|
| 6.1 | Transport |
| Transport in the field | When transporting the equipment in the field, always make sure that you either carry the product in its original container, or carry the tripod with its legs splayed across your shoulder, keeping the attached product upright. |
| Transport in a road vehicle | Never carry the product loose in a road vehicle, as it can be affected by shock and vibration. Always carry the product in its container and secure it. |
| | For products for which no container is available use the original packaging or its equivalent. |
| Shipping | When transporting the product by rail, air or sea, always use the complete ori- ginal Leica Geosystems packaging, container and cardboard box, or its equival- ent, to protect against shock and vibration. |
| — Shipping, transport of batteries | When transporting or shipping batteries, the person responsible for the product must ensure that the applicable national and international rules and regulations are observed. Before transportation or shipping, contact your local passenger or freight transport company. |
| Field adjustment | Exposing the product to high mechanical forces, for example through frequent transport or rough handling, or storing the product for a long time may cause deviations and a decrease in the measurement accuracy. Periodically carry out test measurements and perform the field adjustments indicated in the User Manual before using the product. |
| 6.2 | Storage |
| Product | Respect the temperature limits when storing the equipment, particularly in summer if the equipment is inside a vehicle. Refer to "7 Technical Data" for information about temperature limits. |
| Li-Ion batteries | Refer to "7 Technical Data" for information about storage temperature range. Remove batteries from the product and the charger before storing. After storage recharge batteries before using. Protect batteries from damp and wetness. Wet or damp batteries must be dried before storing or use. A storage temperature range of 0 °C to +30 °C / +32 °F to +86 °F in a dry environment is recommended to minimize self-discharging of the battery. At the recommended storage temperature range, batteries containing a 40% to 50% charge can be stored for up to one year. After this storage period the batteries must be recharged. |

| 6.3 | Cleaning and Drying | |
|------------------------------|--|--|
| Product and accessor- ies | Blow dust off lenses and prisms. Never touch the glass with your fingers. Use only a clean, soft, lint-free cloth for cleaning. If necessary, moisten the cloth with water or pure alcohol. Do not use other liquids; these may attack the polymer components. | |
| Fogging of prisms | Prisms that are cooler than the ambient temperature tend to fog. It is not enough simply to wipe them. Keep them for some time inside your jacket or in the vehicle to allow them to adjust to the ambient temperature. | |
| Damp products | Dry the product, the transport container, the foam inserts and the accessories at a temperature not greater than 40 °C /104 °F and clean them. Remove the battery cover and dry the battery compartment. Do not repack until everything is completely dry. Always close the transport container when using in the field. | |
| Cables and plugs | Keep plugs clean and dry. Blow away any dirt lodged in the plugs of the con- necting cables. | |
| 6.4 | Maintenance | |
| | An inspection of the motorisation in motorised instruments must be done in a Leica Geosystems authorised service centre. Leica Geosystems recommends an inspection of the product every 12 months. For instruments which are in intensive or permanent use, for example tunnel- ling or monitoring, the recommended inspection cycle may be reduced. | |

Technical Data 7 7.1 **Angle Measurement** Accuracy Standard deviation Display resolution Available angular accuracies Hz, V ISO 17123-3 ["] [°] ["] [mgon] [mgon] [mil] 1 0.3 0.1 0.0001 0.1 0.01 2 0.6 0.0001 0.1 0.1 0.01 3 1.0 0.1 0.1 0.0001 0.01 5 1.5 0.0001 0.1 0.1 0.01

Characteristics

Absolute, continuous, diametric.

7.2

Distance Measurement with Reflectors

| Range | Reflector | Range | Α | Range | В | Range C | |
|--------------------|---|-----------|-------|-------|-------|---------|-------|
| | | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| | Standard prism (GPR1) | 1800 | 6000 | 3000 | 10000 | 3500 | 12000 |
| | Three standard prisms (GPR1) | 2300 | 7500 | 4500 | 14700 | 5400 | 17700 |
| | 360° prism (GRZ4, GRZ122) | 800 | 2600 | 1500 | 5000 | 2000 | 7000 |
| | 360° Mini prism (GRZ101) | 450 | 1500 | 800 | 2600 | 1000 | 3300 |
| | Mini prism (GMP101) | 800 | 2600 | 1200 | 4000 | 2000 | 7000 |
| | Reflector tape GZM31) 60 mm x 60 mm | 150 | 500 | 250 | 800 | 250 | 800 |
| | Shortest measuring o | listance: | | 1.5 m | | | |
| Atmospheric condi- | Range | Descri | otion | | | | |

| Atmospheric condi- | Range | Description |
|--------------------|-------|--|
| | A | Strong haze, visibility 5 km; or strong sunlight, severe heat shimmer |
| | В | Light haze, visibility about 20 km; or moderate sun- light, slight heat shimmer |
| | С | Overcast, no haze, visibility about 40 km; no heat shimmer |
| - | | |

B

Measurements can be made to reflector tapes over the entire range without external ancillary optics.

Accuracy

Accuracy refers to measurements to standard prisms.

| Distance measuring mode | Standard deviation ISO 17123-4, standard prism | Standard deviation ISO 17123-4, tape | Measurement time, typical [s] |
|-------------------------------|---|---|----------------------------------|
| Once | 1 mm + 1.5 ppm | 3 mm + 2 ppm | 2.4 |
| Once & fast | 2 mm + 1.5 ppm | 3 mm + 2 ppm | 2.0 |
| Continuously | 3 mm + 1.5 ppm | 3 mm + 2 ppm | < 0.15 |
| Repeatedly & average | 1 mm + 1.5 ppm | 1 mm + 1.5 ppm | - |

Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy.

The display resolution is 0.1 mm.

Characteristics

| Туре | Description |
|------------------|-----------------------------------|
| Principle | Phase measurement |
| Туре | Coaxial, visible red laser |
| Carrier wave | 658 nm |
| Measuring system | System Analyzer Basis 100–150 MHz |

7.3 Distance Measurement without Reflectors (Non-Prism mode)

Range

R500

| Kodak Gray Card | Range D | | Range E | | Range F | |
|-------------------------------|---------|------|---------|------|---------|-------|
| | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| White side, 90 % reflective | 250 | 820 | 400 | 1310 | >500 | >1640 |
| Grey side, 18 % reflective | 150 | 490 | 200 | 660 | >200 | >660 |

R1000

| Kodak Gray Card | Range D | | Range E | | Range F | |
|---|---------|---------------------|-----------------|------|---------|-------|
| | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| White side, 90 % reflective | 800 | 2630 | 1000 | 3280 | >1000 | >3280 |
| Grey side, 18 % reflective | 400 | 1320 | 500 | 1640 | >500 | >1640 |
| Range of Measureme Display unambiguous | nt: | 1.5 m - up to 12 | 1200 m 200 m | | | |

Atmospheric conditions

| Range | Description |
|-------|--|
| D | Object in strong sunlight, severe heat shimmer |
| E | Object in shade, or overcast |

| | Rango | Desc | ription | | | | | | |
|--------------------|---|----------------------------------|---------------------------------|---------------------------|-------------------------|-----------------------------|----------------------------|----------------------|--|
| | | Undo | rground | night a | nd twilig | ht | | | |
| | 1 | | | | | | | | |
| Accuracy | Standard measuring [m] | Stan devia ISO 1 | dard ation [m 17123-4 | Measu mm] typical 4 | | e time, s] | Measure maximun | time, n [s] | |
| | 0-500 | 2 + 2 | ppm | | 3-6 | | 12 | | |
| | > 500 | 4 + 2 | ppm | | 3-6 | | 12 | | |
| | Object in shad moving object accuracy. The display res | e, sky o s within solution | vercast. the bea is 0.1 m | Beam ir m path (m. | nterruptic can resul | ons, severe t in deviati | heat shimr ons of the s | ner and specified | |
| Characteristics | Туре | | Descri | ption | | | | | |
| | Туре | | Coaxial | , visible | red laser | | | | |
| | Carrier wave | | 658 nm | ı | | | | | |
| | Measuring sy | stem | System | Analyze | er Basis 1 | .00–150 M | Hz | | |
| Laser dot size | Distance [m | 1 | Laser o | lot size | , approx | (imately [| mm] | | |
| | at 30 | at 30 | | 7 × 10 | | | | | |
| | at 50 | | 8 × 20 | | | | | | |
| | at 100 | | 16 × 25 | 5 | | | | | |
| 7.4 | Distance M | easur | ement | - Lon | g Rang | e (LO mo | ode) | | |
| Range | The range of t | he long | range m | easurer | nents is t | the same f | or R500 and | d R1000. | |
| | Reflector | | Range | Α | Range | B | Range C | | |
| | | | [m] | [ft] | [m] | [ft] | [m] | [ft] | |
| | Standard pris (GPR1) | m | 2200 | 7300 | 7500 | 24600 | >10000 | >33000 | |
| | Range of mea | Range of measurement: | | it: 1000 m to 12000 m | | | | | |
| | Display unam | biguous | 5. | up to | 12000 m | | | | |
| Atmospheric condi- | Range | | Descri | otion | | | | | |
| tions | A | | Strong heat sh | haze, vi nimmer | sibility 5 | km; or stro | ong sunlight | , severe | |
| | В | | Light ha light, sl | aze, visi ight hea | bility abo at shimm | out 20 km; er | 0 km; or moderate sun- | | |
| | С | | Overca: shimme | st, no ha er | aze, visib | ility about | 40 km; no l | heat | |

Accuracy

| Standard measur- ing | Standard deviation ISO 17123-4 | Measure time, typical [s] | Measure time, maximum [s] |
|-------------------------|--------------------------------------|------------------------------|------------------------------|
| Long Range | 5 mm + 2 ppm | 2.5 | 12 |
| ann interruptions a | avera haat chimma | | to within the beam |

Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy. The display resolution is 0.1 mm.

Characteristics

| Туре | Description |
|------------------|---|
| Principle | Phase measurement |
| Туре | Coaxial, visible red laser |
| Carrier wave | 658 nm |
| Measuring system | System Analyzer Basis 100 MHz - 150 MHz |

7.5

Automatic Target Aiming (ATR)

| Range of tar- | Reflector | Range (Target Aiming) | |
|-------------------------------|---------------------------------|---------------------------------|------------------------|
| get aiming/ target locking | | [m] | [ft] |
| 5 5 | Standard prism (GPR1) | 1000 | 3300 |
| | 360° prism GRZ4, GRZ122) | 800 | 2600 |
| | 360° Mini prism (GRZ101) | 350 | 1150 |
| | Mini prism (GMP101) | 500 | 1600 |
| | Reflector tape 60 mm x 60 mm | 45 | 150 |
| | The maximum example rain. | n range can be restricted by p | poorer conditions, for |
| | Shortest measuring o | listance: 360° prism (Target a | iming): 1.5 m |
| | Shortest measuring c | listance: 360° prism (Target lo | ocking): 5 m |
| ATR accuracy with the | Туре | | Accuracy |
| GPR1 prism | ATR angle accuracy H | Iz, V (std. dev. ISO 17123-3) | 1 " (0.3 mgon) |
| | Base Positioning accu | uracy (std.dev.) | ± 1 mm |
| Searching | Туре | | Value |
| | Typical search time in | n field of view | 1.5 s |
| | Field of view | | 1°25'/1.55 gon |
| | Definable search wind | dows | Yes |
| | | | |
| Characteristics | Туре | Description | |
| | Principle | Digital image processing | |

| Туре | Description |
|------|----------------|
| Туре | Infrared laser |

7.6

Lock

Range of target aiming/ target locking

| Reflector | Range (Target Locking) | | |
|---------------------------------|------------------------------------|------------------------|--|
| | [m] | [ft] | |
| Standard prism (GPR1) | 800 | 2600 | |
| 360° prism GRZ4, GRZ122) | 600 | 2000 | |
| 360° Mini prism (GRZ101) | 200 | 660 | |
| Mini prism (GMP101) | 400 | 1300 | |
| Reflector tape 60 mm x 60 mm | not qualified | | |
| The maximu example rair | m range can be restricted by n. | poorer conditions, for | |

Shortest measuring distance: 360° prism (Target aiming):1.5 mShortest measuring distance: 360° prism (Target locking):5 m

| Maximum speed | in |
|---------------|----|
| lock mode | |

| | Direction of prism movement | | |
|--|-----------------------------|--------|--|
| | Tangential | Radial | |
| Prism Lock only | 14 m/s at 20 m | 25 m/s | |
| Prism Lock with Measure distance: Continuously | 6 m/s at 20 m | 6 m/s | |

A tangential movement means the prism is passing by the instrument at the specified distance.

A radial movement means the prism is moving away from or towards the instrument in the line of sight direction.

SpeedSearch

Range

7.7

Reflector Range [ft] [m] Standard prism 300 1000 (GPR1) 360° prism 1000* 300* (GRZ4, GRZ122) 360° mini prism Not recommended (GRZ101) Mini prism 100 330 (GMP101)

Measurements at the vertical limits of the fan or under unfavourable atmospheric conditions may reduce the maximum range. (*optimally aligned to the instrument)

1.5 m

Shortest measuring distance:

| Searching | Туре | Va | lue | |
|------------------|--|---|---|--|
| | Typical search t | ime 7 | 7 s | |
| | Default search a | area Hz | :: 400 gon, V: 40 gon | 1 |
| | Definable search windows | h Ye | S | |
| Characteristics | Туре | Γ | escription | |
| | Principle | - C | igital signal processi | ng |
| | Туре | Ir | nfrared laser | |
| 7.8 | LOC8 Theft D |)eterren | ce and Location | Device (optional) |
| Internal battery | Battery | Voltage | | Capacity |
| | Li-Ion | 800 mAh Rechargec tion batte is switcheo | l by the total sta- ry when instrument d on | Up to 3 days Depending on mode of oper- ation and cellular network conditions |
| Tracking period | Update rate up to 1 minute | | | |
| Interfaces | Wi-Fi: 802.11 b/g/n | | | |
| Environmental | Temperature | | | |
| specifications | Operating temperature Storag [°C] [°C] | | e temperature | |
| | -20 to +60 | | -20 to | +60 |
| 7.9 | SmartStatior | 1 | | |
| 7.9.1 | SmartStation Accuracy | | | |
| | Measurement precision and accuracy in position and accuracy in height are dependent upon various factors including the number of satellites tracked, constellation geometry, observation time, ephemeris accuracy, ionospheric disturbance, multipath and resolved ambiguities. Figures quoted assume nor- mal to favourable conditions. | | | |
| Accuracy | Туре | | Position accu | racy |
| | Horizontal | | 5 mm + 0.5 pp | m |
| | Vertical | | 10 mm + 0.5 ppm | |

When used within reference station networks the position accuracy is in accordance with the accuracy specifications provided by the reference station network.

Initialisation

| Initialisation | Туре | Description |
|------------------|--|--|
| | Method | Leica SmartCheck+ technology |
| | Reliability of initialisation | Better than 99.99 % |
| | Time of initialisation | Typically 8 s* |
| | Range | Up to 50 km* |
| | * Might vary due to atmospheric signal geometry and number | neric conditions, signal multipath, obstructions, r of tracked signals. |
| RTK data formats | Formats for data reception: | |
| | Leica, Leica 4G, CMR, CMR+, | RTCM 2.2, 2.3, 3.0, 3.1, 3.2 MSM |
| 7.9.2 | SmartStation Dimension | ns |
| SmartStation | With GS16 | |
| | | 190 mm |

7.10 Conformity to National Regulations

7.10.1 TS13

| Conformity to • national regulations • | • | FCC Part 15 (applicable in US) Hereby, Leica Geosystems AG declares that the radio equipment type TS13 is in compliance with Directive 2014/53/EU and other applicable European Directives. The full text of the EU declaration of conformity is available at the fol- lowing Internet address: http://www.leica-geosystems.com/ce. | |
|---|---|--|--|
| | C | Class 1 equipment according to European Directive 2014/53/EU (RED) can be placed on the market and be put into service without restrictions in any EEA member state. | |
| | • | The conformity for countries with other national regulations not covered by the FCC part 15 or European Directive 2014/53/EU has to be approved prior to use and operation. | |

| | Japanese Radio Law and Japanese Telecommunications Business Law Compliance. This device is granted pursuant to the Japanese Radio Law (電波法) and the Japanese Telecommunications Business Law (電気通信事業法). This device should not be modified (otherwise the granted designa- tion number will become invalid). | | |
|---------------------------------------|--|---------------------------------------|--|
| Frequency band | Туре | Frequency Band [MHz] | |
| | Bluetooth | 2402-2480 | |
| | WLAN | 2400–2473, channel 1–11 | |
| Output power | Туре | Output Power [mW] | |
| | Bluetooth | <10 | |
| | WLAN (802.11b) | 50 | |
| | WLAN (802.11g) | 32 | |
| Antenna | Туре | Bluetooth WLAN | |
| | Antenna | Integrated antenna Integrated antenna | |
| | Gain [dBi] | 0 0 | |
| | Connector | | |
| | Frequency band [MH: | 2] 2400–2500 2400–2500 | |
| 7.10.2 | RadioHandle | | |
| Conformity to national regulations | FCC Part 15 (applicable in US) Hereby, Leica Geosystems AG declares that the radio equipment type RadioHandle is in compliance with Directive 2014/53/EU and other applicable European Directives. The full text of the EU declaration of conformity is available at the following Internet address: http://www.leica-geosystems.com/ce. C C Class 1 equipment according to European Directive 2014/53/EU (RED) can be placed on the market and be put into service without restrictions in any EEA member state. The conformity for countries with other national regulations not covered by the FCC part 15 or European Directive 2014/53/EU has to be approved prior to use and operation. Japanese Radio Law and Japanese Telecommunications Business Law Compliance. This device is granted pursuant to the Japanese Radio Law (電波法) and the Japanese Telecommunications Business Law (電気通信事業法). This device should not be modified (otherwise the granted designation number will become invalid). | | |
| | | | |
| | | | |
| | | | |
| Frequency band | Туре | Frequency Band [MHz] | |
| | RH16 | Limited to 2402 - 2480 | |
| RH17 Limited to 2402 - 2480 | | | |
| | | | |

| Output power | Value | | | |
|---------------------------------------|--|--|--|--|
| | < 100 mW (e. i. r. p.) | | | |
| | | | | |
| Antenna | Туре | $\lambda/2$ dipole antenna | | |
| | Gain [dBi] | 2 | | |
| | Connector | Special customized SMB | | |
| 7.10.3 | LOC8 Theft Dete | errence and Location Device (optional) | | |
| Conformity to national regulations | FCC Part 15, 22 and 24 (applicable in US) Hereby, Leica Geosystems AG declares that the radio equipment type LOC8 is in compliance with Directive 2014/53/EU and other applicable European Directives. The full text of the EU declaration of conformity is available at the following Internet address: http://www.leica-geosystems.com/ce | | | |
| | Class 1 equipment according to European Directive 2014/53/EU (RED) can be placed on the market and be put into service without restrictions in any EEA member state. | | | |
| | The conformity for countries with other national regulations not covered by the FCC part 15, 22 and 24 or European Direct- ive 2014/53/EU has to be approved prior to use and operation. | | | |
| | Japanese Radio Law and Japanese Telecommunications Busic Compliance. This device is granted pursuant to the Japanese Radio L and the Japanese Telecommunications Business Law (This device should not be modified (otherwise the gran tion number will become invalid). | | | |
| Specific Absorption Rate (SAR) | The product meets the limits for the maximum permissible exposure of the guide-lines and standards which are force in this respect. The product must be used with the recommended antenna. A separation distance of at least 20 centimetres should be kept between the antenna and the body of the user or nearby person within the intended application. | | | |
| Frequency band | Туре | Value | | |
| | GSM | GSM 900: 880 - 960 MHz GSM 1800: 1710 - 1880 MHz | | |
| | WCDMA | WCDMA 900: 880 - 960 MHz WCDMA 2100: 1920 - 2170 MHz | | |
| | WLAN | 2.4G Wi-Fi 802.11 b/g/n (20 MHz): 2412 - 2472 MHz 802.11 n (40 MHz): 2422 ~ 2462 MHz | | |
| | GPS | 1.57542 GHz | | |
| - | | | | |
| Output power | Туре | Value | | |
| | GSM | GPRS: Maximal power: 29,13 dBm | | |

| Туре | Value |
|-------|--------------------------|
| WCDMA | Maximal power: 23,58 dBm |

| Antenna | Туре | Antenna | Gain | | |
|-----------------|---|--|--|--|--|
| | GSM | Internal PIFA antenna | GSM 900: 0.23 dBi GSM 1800: 0.23 dBi | | |
| | WCDMA | Internal antenna | WCDMA 900: 1.34 dB WCDMA 1200: 1.34 dBi | | |
| | GPS | Internal antenna | 0 dBi | | |
| | WLAN | Internal PIFA antenna | –0.66 dBi | | |
| 7.10.4 | Dangerous | Goods Regulations | | | |
| Dangerous Goods | Many produc | ts of Leica Geosystems are po | wered by Lithium batteries. | | |
| Regulations | Lithium batte safety hazar | thium batteries can be dangerous under certain conditions and can pose afety hazard. In certain conditions, Lithium batteries can overheat and ig | | | |
| | When carrying or shipping your Leica product with Lithium b onboard a commercial aircraft, you must do so in accordance the IATA Dangerous Goods Regulations. Leica Geosystems has developed Guidelines on "How to ca products" and "How to ship Leica products" with Lithium ba Before any transportation of a Leica product, we ask you to these guidelines on our web page (http://www.leica-geosystems.com/dgr) to ensure that you a accordance with the IATA Dangerous Goods Regulations and Leica products can be transported correctly. | | | | |
| | | | | | |
| | e prohibited from being carried or Therefore, ensure that the condi- sportation. | | | | |
| 7.11 | General Technical Data of the Product | | | | |
| System accuracy | Several factor location of a Internal Angular Type and Selected External | ors can influence the accuracy of prism: ATR accuracy accuracy of the instrument d centring accuracy of the prism EDM measuring program measuring conditions | of the system for determining the | | |
| | Therefore, the be lower that | Theretore, the overall pointing accuracy of the determined point location can be lower than the given angular accuracy and the ATR accuracy. | | | |
| | The following and their pos | The following paragraphs provide a short overview of these influencing factors and their possible intensities. | | | |

Angular accuracy

The accuracy of angular measurements depends on the instrument type. The angular accuracy for total stations is typically in the range from 0.5" to 5". The resulting error depends on the measurement distance.

| Angular accuracy | Possible deviation [*] at 100 m distance | |
|------------------------------------|---|--|
| 1″ | ~0.5 mm | |
| 3″ | ~1.5 mm | |
| * Orthogonal to the line of sight. | | |

Refer to the data sheet of the respective instrument model for information about the angular accuracy.

EDM accuracy

The distance measurement accuracy consists of two parts: a fixed value and a distance-dependent value (ppm-value).

Example: "Single measurements: 1 mm + 1.5 ppm"

The EDM accuracies for prism and reflectorless measurements can differ. Additionally, the accuracies can differ depending on the used technologies.

Refer to the appropriate data sheet for information about the EDM accuracy.

ATR accuracy

Automatic target aiming accuracies, like those of the ATR, are in general the same as the stated angular accuracy. Therefore these accuracies are also distance-dependent parameters.

External impacts, like heat shimmer, rain (prism surface covered by rain drops), fog, dust, strong background lights, dirty targets, alignment of the targets etc. can have a significant influence on the automated target. In addition, the selected EDM mode affects the ATR performance. Under good environmental conditions and with a clean, properly aligned target the accuracy of the automated target aiming is equivalent to the manual target aiming (presumed valid calibration values).

Type and centring accuracy of the prism

The prism centring accuracy depends mainly on the used prism type, for example:

| Prism type | | Centring accuracy |
|--------------|--------------------------|-------------------|
| Leica GPR1 | Circular prism | 1.0 mm |
| Leica GPH1P | Precision circular prism | 0.3 mm |
| Leica GRZ122 | 360° prism | 2.0 mm |
| Leica GRZ4 | 360° prism | 5.0 mm |

Refer to the white paper "Leica Surveying Reflectors" for information about the different centring accuracies.

| | More influencing factors When determining absolute of affect the resulting accuracy: Environmental conditions Typical instrument errors error. Proper functioning of lass Correct horizontal levellint Setup of the target Quality of extra equipment | coordinates s: temperat s, such as ho er plummet ng ont, such as | , the following ure, air pressu orizontal collin or optical plu tribrach or trij | parameter re and hu nation err mmet pod. | ers can also midity or or index | |
|------------------------------|--|---|--|--|---------------------------------------|--|
| Telescope | Туре | Value | | | | |
| | Magnification | 30 × | | | | |
| | Free Objective aperture | 40 mm | | | | |
| | Focusing | 1.7 m/5.6 ft to infinity | | | | |
| | Field of view | 1°30'/1.66 gon 2.7 m at 100 m | | | | |
| Compensator | Angular accuracy | Setting accuracy Setting range | | | | |
| | instrument ["] | ["] | [mgon] | ['] | [gon] | |
| | 1 | 0.5 | 0.2 | 4 | 0.07 | |
| | 2 | 0.5 | 0.2 | 4 | 0.07 | |
| | 3 | 1.0 | 0.3 | 4 | 0.07 | |
| | 5 | 1.5 | 0.5 | 4 | 0.07 | |
| Level | Туре | Value | | | | |
| | Circular level sensitivity | 6'/2 mn | n | | | |
| | Electronic level resolution | 2" | | | | |
| Four button keyboard unit | Туре | Description | | | | |
| | Keyboard | 4 keys, | 4 keys, 4 LEDs | | | |
| | Position | Face I only | | | | |
| — Keyboard display unit | Туре | Description | | | | |
| | Display | 5" (inch), WVGA (800*480), colour, touch | | | | |
| | Keyboard | 25 keys, illumination | | | | |
| | Angle display | 360°'", 360° decimal, 400 gon, 6400 mil, V % | | | | |
| | Distance display | m, ft int, ft us, ft int inch, ft us inch | | | | |
| | Position | For both faces optional | | | | |
| | Touch screen | Screen protection foil on glass | | | | |
| | | | | | | |

Instrument ports

| Name | Description | |
|-----------------|---|--|
| Cable | 5 pin LEMO-0 for power, communication, data transfer. This port is located at the base of the instrument. | |
| RadioHandle | Hotshoe connection for RadioHandle This port is located on top of Communication side cover. For this functionality, the TS13 Robotic licence must be purchased. | |
| Bluetooth | Bluetooth module for communication. This port is housed within Communication side cover. | |
| USB host port | • USB memory stick port for data transfer. | |
| USB device port | Cable connections from USB devices for communication and data transfer. | |
| WLAN | WLAN module for Internet access and communication. This port is housed within the Communication side cover. | |

Pin assignments of the 5 pin LEMO-0 port



- Pin 1: Power input а
- Ь Pin 2: not used
- С
- Pin 3: Single ground Pin 4: RxD (RS232, receive d data, In)
- Pin 5: TxD (RS232, transmit е data, Out)
Instrument dimensions



0016264_001





DIGESS5.001

With RH16/RH17



Weight

| Туре | Value |
|------------------|--|
| Instrument | With Four Button Keyboard Unit: 5.0 kg With Keyboard Display Unit: 5.3 kg |
| Tribrach | 0.8 kg |
| Internal battery | 0.2 kg |

Recording

Laser plummet

TS13 with the four button keyboard and without display

Uses the memories only for firmware/license key upload. Data are recorded on the field controller.

TS13 with the full keyboard and with display

Data can be recorded onto a TS card or into the internal memory.

| Туре | Capacity [M | B] Number of measurements per MB |
|---|-------------------------------------|---|
| SD card | 10248192 | 1750 |
| Internal memory | • 2048 | 1750 |
| | | |
| Туре | | Value |
| Type Visible red laser class 2 | | Visible red laser class 2 |
| Location In standing axis of instrument | | In standing axis of instrument |
| Accuracy | | Deviation from plumb line: 1.5 mm (2 sigma) at 1.5 m instrument height |
| Diamotor of | lacor point | 2.5 mm at 1.5 m instrument height |

Technical Data

| Drives | Description | | | | |
|------------------|---|---|---|-----------------------------|--|
| | Endless horizontal and vertical drives | | | | |
| Motorisation | Туре | | Description | | |
| | Maximum rotating | g speed | 50 gon/s | | |
| Power | Туре | I | Description | | |
| | External supply vo | oltage i | Nominal voltage 12.8 V DC, Range 11.5 V-13.5 V | | |
| Internal battery | Туре | Battery | Voltage | Capacity | |
| | GEB222 | Li-Ion | 7.4 V | 6.0 Ah | |
| External battery | Туре | Battery | Voltage | Capacity | |
| | GEB371 | Li-Ion | 13 V | 16.8 Ah | |
| Environmental | Temperature | | | | |
| specifications | Туре | Operating temperature [°C] | | Storage temperature [°C] | |
| | All instruments | -20 to +50 | | -40 to +70 | |
| | Leica SD cards | -40 to + | +80 -40 to +80 | | |
| | Battery internal | -20 to +55 | | -40 to +70 | |
| | Protection against water, dust and sand | | | | |
| | Type Protection | | | | |
| | All instruments IP55 (IEC 60529) | | | | |
| | Humidity | | | | |
| | Type Protection | | | | |
| | All instruments | Max 95% non condensing The effects of condensation are to be effectively counteracted by periodically drying out the instru- ment. | | | |
| Reflectors | Туре | Additive Constant [r | ATR nm] | SpeedSearch | |
| | Standard prism, GPR1 | 0.0 | yes | yes | |
| | Mini prism, GMP101 | +17.5 | yes | yes | |
| | 360° prism, GRZ4 / GRZ122 | +23.1 | yes | yes | |
| | 360° Mini prism, GRZ101 | +30.0 | yes | not recommended | |
| | | | | | |

| | Туре | Additive Constant [mm] | ATR | SpeedSearch | |
|---------------------------------|---|---|--|---|--|
| | Reflector tape S, M, L | +34.4 | yes | no | |
| | Reflectorless | +34.4 | no | no | |
| | There are no specia | al prisms required fo | or ATR or fo | r SpeedSearch. | |
| Electronic Guide Light | Туре | Desci | ription | | |
| EGL | Working range | 5 m te | o 150 m (15 | 5 ft to 500 ft) | |
| | Position accuracy | 5 cm | at 100 m (1 | 97" at 330 ft) | |
| Automatic corrections | The following autor Line of sight e Tilting axis err Earth curvatur Circle eccentr | matic corrections ar error ror re icity | e made: | | |
| _ | Compensator index error Vertical index error Standing axis tilt Refraction ATR zero point error | | | | |
| 7.12 | Scale Correction | on | | | |
| Use of scale correction | By entering a scale taken into account • Atmospheric co • Reduction to n • Projection diste | correction, reductio prrection. nean sea level. ortion. | ons proport | ional to distance can be | |
| Atmospheric correc- tion ∆D1 | The slope distance which has been en at the time of the i | displayed is correct tered corresponds t measurement. | if the scale o the atmo | e correction in ppm, mm/km, spheric conditions prevailing | |
| | The atmospheric correction includes:Adjustments for air pressureAir temperatureRelative humidity | | | | |
| | For highest precision distance measurements, the atmospheric correction should be determined with an accuracy of 1 ppm. The following parameters must be redetermined: Air temperature to 1 °C Air pressure to 3 mbar Relative humidity to 20% | | | | |
| Air humidity | The air humidity in extremely hot and For high precision r entered along with | fluences the distanc damp. measurements, the the air pressure an | e measurer relative hur d the temp | nent if the climate is nidity must be measured and erature. | |

| Air humidity correction | ррт +5 +4 +3 +2 +1 +0 -20 -10 0 10 20 30 40 50 | 100% 80% 60% 20% ppm 20% % 0 °C %С | Air humidity correction [mm/km] Relative humidity [%] Air temperature [°C] |
|---|---|--|---|
| Index n | Туре | Index n | Carrier wave [nm] |
| | Combined EDM | 1.0002863 | 658 |
| | The index n is calculated from t is valid for: Air pressure p: Air temperature t: Relative air humidity h: | he formula of th 1013.25 mbar 12 °C 60% | e IAG Resolutions (1999), and |
| Formulas | Formula for visible red laser $\Delta D_1 = 286.338 - \left[\frac{0.29535 \cdot p}{(1 + \alpha \cdot t)} - \frac{4.126 \cdot (1 + \alpha \cdot t)}{(1 + \alpha \cdot t)} - \frac{4.126 \cdot (1 + \alpha \cdot t)}{(1 + \alpha \cdot t)} \right]$ $\Delta D_1 \text{Atmospheric correction [} p \text{Air pressure [mbar]} \\ t \text{Air temperature [oc]} \\ h \text{Relative humidity [%]} \\ \alpha \frac{1}{273.15} \\ x (7.5 * t/(237.3 + t)) + 0. \\ If the basic value of 60 \% relating maximum possible error in the signal of the$ | <u>10⁻⁴ · h</u> · 10 ^x) ppm] 7857 ve humidity as us calculated atmos | sed by the EDM is retained, the pheric correction is 2 ppm, |
| Reduction to mean sea level ∆D ₂ | The values for ΔD_2 are always mula: $\Delta D_2 = -\frac{H}{R} \cdot 10^6$ | ΔD_2 Reducti H Height R 6.378 * | derived from the following for- on to mean sea level [ppm] of EDM above sea level [m] ^r 10 ⁶ m |
| Projection distortion ΔD_3 | The magnitude of the projection system used in a particular court | n distortion is in ntry, for which o | accordance with the projection fficial tables are generally |

available. The following formula is valid for cylindrical projections such as that of Gauss-Krüger:

Х

$$\Delta D_{3} = \frac{\chi^{2}}{2R^{2}} \cdot 10^{6}$$

 ΔD_3 Projection distortion [ppm]

Easting, distance from projection zero line with the scale factor 1 [km]

R 6.378 * 10⁶ m

In countries where the scale factor is not unity, this formula cannot be directly applied.

Atmospheric corrections °C

Atmospheric corrections in ppm with temperature [°C], air pressure [mb] and height [m] at 60% relative humidity.



Atmospheric corrections °F

Atmospheric corrections in ppm with temperature [°F], air pressure [inch Hg] and height [ft] at 60% relative humidity.



Reduction Formulas

Reflector types

7.13

The reduction formulas are valid for measurements to all reflector types:

- To prisms
- To reflector tape
- Reflectorless measurements

Slope distance - corrections

Available formats depend on the instrument.

| Format | | Description | | |
|-------------|---|-------------|---|--|
| • • • | Instrument display DBX ASCII GSI | • | Corrections for the atmospheric ppm are applied to the slope distances according to the formulas. | |
| • | XML export | • | Output without corrections for the atmospheric ppm ppm is stored as metadata Corrections are applied during later input, for example to Infin- ity | |

Formulas



The instrument calculates the slope distance, horizontal distance, height difference in accordance with the following formulas:

$$= D_0 \cdot (1 + ppm \cdot 10^{-6}) + AC$$

∠ Displayed slope distance [m]

- D₀ Uncorrected distance [m]
- ppm Atmospheric scale correction [mm/km]
- AC Additive constant of the reflector [m]

| Distance measuring program Averaging | In the distance measuring program Averaging, the following values are dis- played: D Slope distance as arithmetic mean of all measurements s Standard deviation of a single measurement n Number of measurements |
|---|---|
| | These values are calculated as follows: |
| | $\begin{split} \overline{D} &= \frac{1}{n} \cdot \sum_{i=1}^{n} D_i \\ \overline{D} & \text{Slope distance as arithmetic mean of all measurements} \\ \Sigma & \text{Sum} \\ D_i & \text{Single slope distance measurement} \\ n & \text{Number of measurements} \end{split}$ |
| | $S = \sqrt{\frac{\sum_{i=1}^{n} (D_i - \overline{D})^2}{n - 1}} = \sqrt{\frac{\sum_{i=1}^{n} D_i^2 - \frac{1}{n} (\sum_{i=1}^{n} D_i)^2}{n - 1}}$ |
| | $\begin{array}{lll} s & \mbox{Standard deviation of a single slope distance measurement} \\ \Sigma & \mbox{Sum} \\ \overline{D} & \mbox{Slope distance as arithmetic mean of all measurements} \\ D_i & \mbox{Single slope distance measurement} \\ n & \mbox{Number of distance measurements} \end{array}$ |
| | The standard deviation ${}^{S}{}_{\overline{D}}$ of the arithmetic mean of the distance can be calculated as follows: |
| | $S_{\overline{D}} = \frac{S}{\sqrt{n}}$ |
| | |

- $S_{\overline{D}}$ Standard deviation of the arithmetic mean of the distance
- Standard deviation of a single measurement Number of measurements S
- n

| 8 | Software Licence Agreement |
|-------------------------------|--|
| Software Licence Agreement | This product contains software that is preinstalled on the product, or that is supplied to you on a data carrier medium, or that can be downloaded by you online according to prior authorisation from Leica Geosystems. Such software is protected by copyright and other laws and its use is defined and regulated by the Leica Geosystems Software Licence Agreement, which covers aspects such as, but not limited to, Scope of the Licence, Warranty, Intellectual Prop- erty Rights, Limitation of Liability, Exclusion of other Assurances, Governing Law and Place of Jurisdiction. Please make sure, that at any time you fully comply with the terms and conditions of the Leica Geosystems Software Licence Agreement. |
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| Open Source information | The software on the product may contain copyright-protected software that is licenced under various open source licences. |
| | Copies of the corresponding licences are provided together with the product (for example in the About panel of the software) can be downloaded on http://opensource.leica-geosystems.com |
| | If foreseen in the corresponding open source licence, you may obtain the cor- responding source code and other related data on http://opensource.leica-geosystems.com. Contact opensource@leica-geosystems.com in case you need additional information. |
| | |

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